







RIL400 - 405 - 410 - 415 - 420 - 425 Operating Instruction



# INDEX:

		0
1.	About this document	pag. 3
2.	For your safety	pag. 4
3.	Product description	pag. 5
4.	Product Overview	pag. 6
5.	The Installation Requirements	pag. 7
6.	Structure Drawing	pag. 14
7.	Technical Parameters	pag. 16
-		
8.	Meter Linearity	pag. 17
9.	Electrical Connection	pag. 18
10.	Operation Instructions	pag. 22
11.	Troubleshooting	pag. 34



## 1 About this document

## 1.1 Function

This operating instructions provides all the information you need for mounting, connection and setup as well as important instructions for maintenance, fault rectification, the exchange of parts and the safety of the user. Please read this information before putting the instrument into operation and keep this manual accessible in the immediate vicinity of the device.



## 1.2 Target group

This operating instructions manual is directed to trained personnel. The contents of this manual must be made available to the qualified personnel and implemented.



## 1.3 Symbols used

### Document ID

This symbol on the front page of this instruction refers to the Document ID. By entering the Document ID on www.riels.com you will reach the document download.

## 1.4 Information, tip, note

This symbol indicates helpful additional information.



## Caution:

If this warning is ignored, faults or malfunctions can result.



# Warning:

If this warning is ignored, injury to persons and/or serious damage to the instrument can result.



#### Danger:

If this warning is ignored, serious injury to persons and/or destruction of the instrument can result.



## 2 For your safety



## 2.1 Authorised personnel

All operations described in this documentation must be carried out only by trained, qualified personnel authorised by the plant operator. During work on and with the device, the required personal protective equipment must always be worn.



## 2.2 Appropriate use

RIL40X is a sensor for continuous level measurement. You can find detailed information about the area of application in chapter "Product description". Operational reliability is ensured only if the instrument is properly used according to the specifications in the operating instructions manual as well as possible supplementary instructions.



## 2.3 Warning about incorrect use

Inappropriate or incorrect use of this product can give rise to application-specific hazards, e.g. vessel overfill through incorrect mounting or adjustment. Damage to property and persons or environmental contamination can result. Also, the protective characteristics of the instrument can be impaired.



## 2.4 General safety instructions

This is a state-of-the-art instrument complying with all prevailing regulations and directives. The instrument must only be operated in a technically flawless and reliable condition. The operator is responsible for the trouble-free operation of the instrument.

When measuring aggressive or corrosive media that can cause a dangerous situation if the instrument malfunctions, the operator has to implement suitable measures to make sure the instrument is

functioning properly. During the entire duration of use, the user is obliged to determine the compliance of the necessary occupational safety measures with the current valid rules and regulations and also take note of new regulations.

The safety instructions in this operating instructions manual, the national installation standards as well as the valid safety regulations and accident prevention rules must be observed by the user.

For safety and warranty reasons, any invasive work on the device beyond that described in the operating instructions manual may be carried out only by personnel authorised by the manufacturer. Arbitrary conversions or modifications are explicitly forbidden.

For safety reasons, only the accessory specified by the manufacturer must be used. To avoid any danger, the safety approval markings and safety tips on the device must also be observed and their meaning read in this operating instructions manual.

Depending on the instrument version, the emitting frequencies are in the C, K or W band range. The low emission power is far below the internationally approved limit values. When used correctly, the device poses no danger to health.

### 2.5 EU conformity

The device fulfils the legal requirements of the applicable EU directives. By affixing the CE marking, we confirm the conformity of the instrument with these directives.

Electromagnetic compatibility Instruments in four-wire version are designed for use in an industrial environment. Nevertheless, electromagnetic interference from electrical conductors and radiated emissions must be taken into account, as is usual with class A instruments according to EN 61326-1. If the instrument is used in a different environment, the electromagnetic compatibility to other instruments must be ensured by suitable measures.

#### 2.6 Warranty

Products supplied by Riels Instruments srl are guaranteed for a period of 12 (twelve) months from delivery date according to the conditions specified in our sale conditions document. Riels Instruments srl can choose to repair or replace the Product. If the Product is repaired it will maintain the original term of guarantee, whereas if the Product is replaced it will have 12 (twelve) months of guarantee. The warranty will be null if the Client modifies, repair or uses the Products for other purposes than the normal conditions foreseen by instructions or Contract. In no circumstances shall Riels Instruments srl be liable for direct, indirect or consequential or other loss or damage whether caused by negligence on the part of the company or its employees or otherwise howsoever arising out of defective goods.



## **3 Product description**

## 3.1 Configuration

Instrument type
 Product code
 Working temperature
 Working pressure
 Output signals
 Power supply
 Measuring range
 Degree protection
 serial number

10 Logo riels instruments

11CE logo

The type label contains the most important data for identification and use of the instrument:



Fig. 1: Layout of the type label (example)



## 4. Product Overview

This series of radar level meter adopted 26G high frequency radar sensor, the maximum measurement range can reach up to 80 meters. Antenna is optimized further processing, the new fast microprocessors have higher speed and efficiency can be done signal analysis, the instrumentation can be used for reactor, solid silo and very complex measurement environment.

#### 4.1 Principle

Radar level transmitter antenna microwave pulse is narrow, the downward transmission antenna. Microwave exposure to the medium surface is reflected back again by the antenna system receives, sends the signal to the electronic circuit automatically converted into level signals (because the microwave propagation speed, electromagnetic wave to reach the target and the reflected back to the receiver this time is almost instantaneous).



- B Low adjustment
- C High
- D Blind area



Datum measurement: Screw thread bottom or the sealing surface of the flange.

**Note:** Make sure the radar level meter the highest level cannot enter the measuring blind area (Figure D shown below).

#### 4.2 The characteristics of 26G radar level meter:

- Small antenna size, easy to install; Non-contact radar, no wear, no pollution.
- Almost no corrosion, bubble effect; almost not affected by water vapor in the atmosphere, the temperature and pressure changes.
- Serious dust environment on the high level meter work has little effect.
- A shorter wavelength, the reflection of solid surface inclination is better.
- Beam angle is small, the energy is concentrated, can enhance the ability of echo and to avoid interference.
- The measuring range is smaller, for a measurement will yield good results.
- High signal-to-noise ratio, the level fluctuation state can obtain better performance.
- High frequency, measurement of solid and low dielectric constant of the best choice.



## 5. The Installation Requirements

- A Range setting
- B Min adjustment
- Max adjustment С
- D Near blanking

A Range setting B Min adjustment Max adjustment

D Near blanking

С



#### Note:

The reference surface for measurement: the bottom surface of the thread or the sealing surface of the flange. When using radar level meter, make sure that the highest material level cannot enter the blind area of the measurement (the area shown in D(near blanking)in the figure).

When setting the range parameter, be sure to include the height of the conical part of the tank (refer to A in the figure).



#### 5.1 Installation guide:

The radar level transmitter has to be installed in the diameter of the 1/4 or 1/6.

Note: The minimum distance from the tank wall should be 200mm.

Note: (1) datum plane (2) The center of the container center or symmetrical

The top plane of the conical tank can be installed in the middle of the tank top, It is guaranteed to measure to the bottom of the cone.





When there is a stockpile, the antenna should be vertically aligned with the material surface. If the material level is Uneven, large pile angle must be adjusted with universal flange The angle of the horn makes the horn aim at the material surface as much as possible.

(Because the inclined solid surface will cause echo attenuation, Even the problem of signal loss)



#### Stir

When there is stirring in the tank, keep the meter away from the stirrer if necessary.

After installation, "false echo learning" should be carried out under agitation, In order to eliminate the false echo effect generated by the stirring blade.

If foam or waves rise due to stirring, The installation should use wave guide pipe.





#### False echo storage

When there is a stirring blade in the tank that interferes with the radar measurement, if the stirring blade cannot be avoided, a false return is required.

Wave storage eliminates interference signals generated by false waves.



If you want to get the normal level echo, the false echo storage can store the echo signal between the envelope curve in the figure below, the storage is defined as a false signal, and a normal level echo signal is obtained.





#### Guide wave pipe installation

Use guide wave pipe installation (guide wave pipe or by pass pipe), can avoid obstacles and foam influence on the measurement.

Due to feeding, mixing or others process handling in the container, it will generate foam on the surface of some liquids, the signal will be attenuate.

If bubbles cause measurement errors, you should Install the sensor in the guide wave pipe, or use guided wave radar level meter.

Measure inside the guide wave pipe, the guide wave minimum diameter is 50mm. In the connection guide Wave pipe, should avoid big cracks and Weld. In addition, carry out"virtual False echo learning".

Note: while measure adhesive medium, Should not use guide wave pipe.





#### Design requirements for guide wave pipe:

- Metal material, smooth inside the tube;
- Preferably stretched or longitudinal welded stainless steel pipe;
- The weld must be as flat as possible and coaxial with the hole;
- While using pre-welded flanges or extending the sleeves and using a ball valve, the transition pipe must be aligned on the inside and Fix after accurate matching;
- The gap on the transition pipe is ≤0.1mm;
- Do not weld along the pipe wall. The inner wall of the guide wave pipe must remain flat and smooth. If user accidentally weld the inside, you should remove the uneven places and weld bead. otherwise it will cause serious interference echo, so as to bring convenience to the attachment of the medium;
- Guide wave pipe must reach at least the desired minimum filling height,
- Because the measurement can only be carried out in the tube;
- Aperture ≤5mm, any number, single side or full pass;
- The antenna diameter of the sensor should be as consistent as possible
- with the inner diameter of the pipe;
- The diameter should be consistent throughout the length;

### 5.2 Typical installation errors

### Typical wrong installation:

The conical tank cannot be installed above the inlet. At the same time: when installing outdoors, user should take sun-shading and rain-proof measures





- (1) Radar sensor
- 2 Thread or flange
- ③ Exhaust hole
- (4) Isobaric hole
- 5 Welding seam
- 6 Butt welding flange with neck
- 7 Fixing of wave tube





The meter cannot be installed in the middle of an arched or round tank top. In addition to generate indirect echo, but also influenced by the echo, multiple echoes may be larger than the signal threshold of true echoes, because they can be concentrated through the top. Therefore, it cannot be installed in the central location.





When there are obstacles in the tank that affect the measurement, it is necessary to install a reflecting plate to measure normally.





Deflect the obstacle signal away



## Height of nozzle:

Adapter height requirements: it needs guarantee that the antenna extends into the tank at least 10mm.







d	h
80 mm (3")	150 mm
100 mm (4")	300 mm
150 mm (6")	500 mm



# 6. Structure Drawing

Model RIL400





Model RIL405





Flange	The bell Diameter D	Bell Heigh H
DN50	ø 46	140
DN80	ø 76	227
DN100	ø 96	288

Model RIL410



Flange	The bell Diameter D	Bell Heigh H
DN80	ø 76	227
DN100	ø 96	288
DN125	ø 121	620





D



# 7. Technical Parameters

The outer shell	
The seal between the shell and the shell cover:	Silicone rubber
Casing window:	Polycarbonate
The ground terminal:	Stainless steel
The power supply voltage	
Two wire system	
The standard type:	(1626) V DC
Intrinsically safe:	(21.626.4) V DC
Power dissipation:	max 22.5mA / 1W
Allowable ripple	- <100Hz Uss <iv - (100÷100K) Hz Uss<i0mv< td=""></i0mv<></iv 
The cable parameters	
Cable entrance / plug	1 M20xl.5 cable entrance 1 blind plug
Terminal	Conductor cross section 2.5mm <sup>2</sup>
Output parameters	
The output signal	(4÷20) mA/RS485
Communication protocol	HART
Resolution	1.6µА
Fault signal	Constant current output; 20.5mA 22mA 3.9mA
The integral time	(050) s, adjustable
Blind area	the ends of the antenna
The maximum distance measurement	80 meters
Microwave frequency	26GHz
Communication interface	HART communication protocol
The measurement interval	about 1 second (depending on the parameter settings)
Adjust the time	about 1 second (depending on the parameter settings)
Display resolution	1 mm
Working storage and transportation temperature	-40°C+100°C
Process temperature (the temperature of the a	ntenna part)
RIL400	-40°C+130°C
KIL405/410/415/420 RIL425	-40°C+250°C -40°C+150°C
Pressure	Max.4MPa
Seismic	Mechanical vibration I0 m/s <sup>2</sup> , (10÷150) Hz



## 8. Meter Linearity



## Model RIL410

30mm	
15mm	
1.0m	70m
-15mm	
-30mm	

Emission angle	Depending on the size of the antenna
ø 46 mm	18°
ø 76 mm	12°
ø 96 mm	8°
ø 121 mm	6°
Precision	See chart



Model DII 115			
WUUUU NIL413			
	30mm + ×		
	15mm	<b>`</b>	
		1.0m	70m
	-15mm	1.0m	7011
	Emission angle	Depending on the size of the antenna	
	ø 196 mm	4°	
	ø 242 mm	4°	
	Precision	See chart	
Model RIL420			
	20mm		
	10mm —	<b></b>	
		0.5m	30m
	-10mm		
	20mm		
	Emission angle	Depending on the size of the antenna	
	ø 76 mm	12°	
	ø 96 mm	18°	
	ø 121 mm	6°	
	Precision	See chart	
Model RII 125			
WUUGI NIL420			
	20mm - N	<	
	3mm -	<b>\</b>	
	3mm	0.5m	20m
	-20mm		
	Emission anale	Depending on the size of the antenna	
	ø 46	18°	
	ø 76	12°	
	ø 96	8°	
	Precision	See chart	



## 9. Electrical Connection

## 9.1 Supply Voltage

Cable requirements

The power supply cable can use ordinary two-core cables, and the outer diameter of the cable should be (8...12)mm to ensure the sealing of the cable entrance. If there is electromagnetic interference, it is recommended to use shielded cables.

### 9.2 (4÷20) mA/HART (two wire system)

The power supply and output current signal share a two-core shielded cable. Refer to technical data for specific power supply voltage range, for intrinsic safety type, a safety barrier must be added between the power supply and the instrument.

### 9.3 (4÷20) mA/HART(four wire system)

The power supply and the current signal are separated, refer to technical data for specific power supply voltage range, a two-core shielded cable is used for each.

### 9.4 RS485/Modbus

Separate the power supply and the 485 signal line using a two-core shielded cable. For the specific power supply voltage range, refer to the technical data.

## 9.5 Connection type

The wiring diagram of 24V two-wire system as below:



The wiring diagram of 24V four-wire system as below:



24V/12V RS485/Modbus Wiring Diagram





### 9.6 Safety Guidance

Please comply with the requirements of local electrical installation regulations! Please abide by local regulations and requirements for personnel health and safety. All operations on the electrical components of the instrument must be completed by formal trained professionals. Please check the nameplate of the meter to ensure that the product specifications meet your requirements. Please make sure that the power supply voltage is consistent with the requirements in the nameplate.

#### 9.7 Protection Class

This instrument fully meets the requirements of protection class IP66/67. Please ensure the waterproofness of the cable sealing head. Such as the following figure:

How to ensure that the installation meets the requirements of IP67: Make sure that the sealing head is not damaged. Make sure that the cables is not damaged. Make sure that the cables used meet the requirements of the electrical connection specifications. Before entering the electrical interface, bend the cable downward to ensure water will not flow into the shell, see (1)Please tighten the cable sealing head, see (2)Please block the unused electrical interface with blind plug, see (3)

### 9.8 Debugging

Three debugging methods:

- 1 LCD display /Button
- (2) Upper Computer debugging
- (3) HART handheld programmer

#### 9.9 LCD display /Button

Debug the meter through the 4 buttons on the display screen. The language of the debugging menu is selectable. After debugging, It is generally only used for display, and the measured value can be read very clearly through the glass window.





## 9.10 Computer Debugging

- Connect with computer via HART
- USB
   Radar level meter
   HART adapter
   250Ω Resistor



## 9.11 HART Hand-held Programmer Programming

HART handheld programmer
 Radar level meter
 250Ω Resistor





# 10. Operation Instructions

<ul> <li>10. Basic Settings (1)</li> <li>From "RUN" mode press is to enter the configuration menu. Press is to select and to confirm. The menu item number is always displayed on the top right corner. By selecting and confirming "Basic settings" in menu 1, the display will show in sequence:</li> <li>10.1 Min. adjustment (1.1)</li> <li>Press is to modify the percentage value (see par. 2.4). Press is again to confirm and to edit the corresponding distance value. After the setup press is to confirm. Press is to enter menu 1.2.</li> <li>Note:</li> <li>The lower value (d) shows the measured instantaneous distance.</li> </ul>	<ul> <li>Basic settings 1 Display Diagnostics Service Info</li> <li>Min adjustment 1.1 0,00% 35,000 m (d)</li> <li>25.346m (d)</li> </ul>	Select menuOKConfirmNote-The menu item number is displayed on the top right corner.OKEnter editing menuOKSelect the valueOKConfirmOKConfirmOKGo to menu 1.2
<b>10.2 Max adjustment (1.2)</b> Press INF to modify the percentage value (see par. <b>2.4</b> ). Press INF again to confirm and to edit the corresponding distance value. After the setup press INF to confirm. Press I to enter menu <b>1.3</b> Note- The lower value (d) shows the measured istantaneous distance.	Max adjustment 1.2 100,00% 0,000 m (d) 1.346m (d)	<ul> <li>OK Enter editing menu</li> <li>Select the value</li> <li>Modify the value</li> <li>OK Confirm</li> <li>Go to menu 1.3</li> </ul>
10.3 Medium (1.3) Each medium has different reflective properties. In this menu is possible to choose between liquid or solid medium. Press ok to enter medium selection menu.	Medium 1.3 liquid	OKEnter editing menuImage: Confirm and enter submenuImage: Confirm and enter submenu<
Press C to select the medium and on to confirm and to enter submenu 1.3.1	Medium 1.3 Iiquid solid Micro DK	OK       Select the medium type         Confirm the selection
<ul> <li>10.3.1 Fast level change (1.4)</li> <li>Transient or foreign elements could temporary cause unexpected rushes in measured values. In these events set the parameter on "No"in order to filter the rushes. Default setting is "Yes".</li> <li>Press or to enter parameter modification, press S to enter the next menu</li> <li>1.5</li> </ul>	Fast level change 1.3.1 Yes ►	OKEnter editing menuCGo to submenu 1.5
With 🔁 you can select the parameter setting, with 🚾 you can confirm your selection and go back to previous submenu.	Fast level change 1.3.1 Yes No	Select parameter OK Confirm and go back to previous submenu



<b>10.3.2 First echo (1.3.2)</b> This parameter sets the first valid echo signal acceptance . Press <sup>™</sup> to enter parameter modification, press <sup>™</sup> to enter the next submenu <b>1.3.3</b> (par.3.3.c).	First Echo 1.3.2 Normal ►	OKEnter editing menuCo to next submenu 1.3.3.
With 🔁 you select the parameter setting, with 🚾 you confirm your se- lection and go back to previous submenu: - Normal; automatic - Small; decrease first echo by 10dB - Big; increase first echo by 10dB - Bigger; decrease first echo by 40dB - Biggest; increase first echo by 40dB	First Echo 1.3.2 ►Normal Big Small Bigger Biggest	Select parameter Confirm and go to back to previous submenu
<ul> <li>10.3.3 Agitated surface (1.3.3)</li> <li>Large angle repose (1.3.3)</li> <li>This submenu is related to the previous selection in menu 1.3: by selecting "Liquid" in menu 1.3, the display will now show "Agitated surface";</li> <li>In both cases the default setting is "No".</li> <li>Press ∞ to enter parameter modification, press to  enter the next submenu.</li> </ul>	Agitated surface 1.3.3 No ► Agitated surface 1.3.3 Yes ►No	OK       Enter editing menu         Image: Construct of the symptotic of the symptotic of the symptote of the symptotic of the symptote of t
By selecting <b>"Solid</b> " in menu 1.3, the display will now show <b>"Large angle repose</b> ". Press <b>o</b> to enter parameter modification, press <b>o</b> to enter the next submenu.	Large angle repose 1.3.3 No ►	OK       Enter editing menu         OK       Enter editing menu         OK       Go to next submenu 1.3.4.         Note - This window is diplayed only in case of selected option "Solid" in menu 1.3
	Large angle repose 1.3.3 Yes ►No	Select parameter OK Confirm and go to back to previous submenu



10.3.4 Foaming (1.3.4) Powder dust (1.3.4)	Foaming 1.3.4	<b>OK</b> Enter editing menu
This submenu is related to the previous selection in menu 1.3: by selecting "Liquid" in menu 1.3, the display will now show "Foamimg" In both cases the default setting is "No".	No ►	Go to next submenu 1.3.5. <u>Note - This window is diplayed</u> <u>only in case of selected option</u> <u>"Liquid" in menu 1.3</u>
Press 🚾 to enter editing menu and press 🔁 to select the option. Then press 🚾 again to confirm and to go	Foaming 1.3.4 Yes No	Select parameter <b>Confirm</b> and go to back to previous submenu
by selecting "Solid" in menu 1.3, the display will now show "Powder dust".	Powder dust 1.3.4 No ►	OK       Enter editing menu         Image: Construct on the system of the sy
Press 🚾 to enter editing menu and press 🔁 to select the option. Then press 🚾 again to confirm and to go	Fast level change 1.3.1 Yes ►	OK       Enter editing menu         Image: Go to next submenu
10.3.5 Low DK (1.3.5) The Dielectric Constant is very important in order to obtain a correct me- asurement. In case of products with low dielectric costant (absestos or non-conductive liquids), set the parameter on "Yes". The default setting is "No". Press of to enter parameter modification and press of to select the parameter	Low DK 1.3.5 No ►	OK       Enter editing menu         Image: Constant submenu       Go to next submenu         Note - This window is diplayed       only in case of selected option         Image: Constant submenu       1.3
Press of again to confirm and to go back to previous submenu.	Low DK 1.3.5 Yes No	Select parameter OK Confirm
Selecting " <b>Yes</b> " must enter the height of empty vessel. Press ⋘ again and enter the Empty Span. Press ⋘ to confirm and ☎ to go back to previous submenu.	Low DK 1.3.5 Yes Empty Span 10.00m	<ul> <li>OK Enter editing menu</li> <li>Select the value</li> <li>Modify the value</li> <li>OK Confirm</li> <li>Go to the next menu</li> </ul>



<b>10.3.6 Measure in tube (1.3.6)</b> This window is displayed only by selecting "Liquid" in menu 1.3. If the transmitter is installed into a calm or by pass pipe it is necessary to set "Yes". The default setting is "No".	Measure in tube 1.3.6 No ►	OK       Enter editing menu         Image: Construct on the symptotic onter the symptotic ontend ontend onter the symptotic onter the symptotic ont
Press M to enter parameter modification and press M to make the se- lection. Confirm with M and go next submemu "Measure diameter".	Measure in tube 1.3.6 Yes No	Select parameter CK Confirm and go to the next submenu
Press again <sup>IMK</sup> and enter the diameter value, as specified in par. <b>2.4</b> . Press <sup>IMK</sup> to confirm and <sup>CD</sup> to go back to previous submenu.	Measure in tube 1.3.6 Measure diamet 0000mm	<ul> <li>OK Enter editing menu</li> <li>Select the value</li> <li>Modify the value</li> <li>OK Confirm</li> </ul>
<ul> <li>10.3.7 Micro DK (1.3.1)</li> <li>Normally when electronic constant is smaller than 1.4, the direct echo from the medium is low and hard to detect.</li> <li>However by measuring the echo reflected from the base of the vessel, the height of the medium can be measured.</li> <li>Two parameters are needed to be entered here.</li> <li>Height of empty vessel.</li> <li>True medium height or medium electronic constant, these two parameters are related, entering either one is accepted.</li> <li>The precision of parameters will affect the precision of the measurement.</li> </ul>	Medium       1.3         liquid       solid         ► Micro DK       1.3.1         Empty Span       10.00m         True level       0.00m         DK       1.00	OK       Enter editing menu         C       Go to next submen         OK       Enter editing menu         C       Select the value
<b>10.4 Damping (1.4)</b> Press <sup>OK</sup> to enter parameter modification and set the value (in seconds) and confirm with <sup>OK</sup> . Press <sup>CD</sup> to go to next menu <b>1.5</b> .	Damping 1.4 ØS	<ul> <li>OK Enter editing menu</li> <li>Select the value</li> <li>Modify the value</li> <li>OK Confirm</li> <li>Go to the next menu 1.5.</li> </ul>
10.5 Mapping curve (1.5) The relationship between the measured value and the output signal 4÷20mA can be linear or non linear. In this menu you can set the output signal 4÷20mA: "linear" or "non- line- ar". The setting of "non- linear" mode must be done with software through PC. Press of to select the 4÷20mA output mode, press is to enter the next menu	Mapping curve 1.5 Linear ►	OK Enter editing menu Go to next submenu 1.6. <u>Note -The setting of a "non-line-</u> <u>ar" mapping curve must be done</u> <u>withsoftware through PC</u>



10.6 Scaled units (1.6) Press <sup>™</sup> to enter parameter modification. Press <sup>™</sup> to go to next menu 1.7.	Scaled units 1.6 height► m ►	OKEnter editing menuCGo to next submenu 1.7.
The selectable options are: - Height; m, ft, in, cm, mm - Mass; Kg, t, lb - Flow; m3/s, m3/h, ft3/s, ft3/m, gal/s, gal/min, gal/h, l/s, l/min, l/h - Volume; m3, l, hl, ft3, in3 Press ♀ to make the selection and ♥ press to confirm	Scaled units 1.6 ► Height Volume Weight No unit Flow	Select parameter Confirm and enter to rele- vant submenu
10.7 Scaling (1.7)         Press INF to modify the 0% value, press INF to enter the next menu.         Set the value and confirm with INF.         Press INF again to modify the 100% value. Set the value and confirm. Press         INF to enter the next menu.	Scaling 1.7 0%= 0.00 100%= 0.00 m	OKEnter editing menuImage: Select the valueImage: Select t
10.8 Range (1.8) Press I to modify the value expressed in meters, press I to enter the next menu 1.9. Set the value and confirm with II. Press I to enter the next menu 1.9.	Range 1.8 31.000 m (d)	<ul> <li>OK Enter editing menu</li> <li>Select the value</li> <li>Modify the value</li> <li>OK Confirm</li> <li>Go to the next menu 1.9.</li> </ul>
10.9 Near blanking (1.9) Press <sup>OK</sup> to modify the value expressed in meters, press <sup>CC</sup> to enter the next menu 1.10 Set the value and confirm with <sup>OK</sup> . Press <sup>CC</sup> to enter the next menu 1.9.,	Near blanking 1.9 0.400 m (d)	<ul> <li>OK Enter editing menu</li> <li>Select the value</li> <li>Modify the value</li> <li>OK Confirm</li> <li>Go to the next menu 1.9.</li> </ul>
10.10 Sensor tag (1.10) Press <sup>™</sup> to modify the parameter, press <sup>™</sup> to enter the starting menu 1.1. Set the value, as specified in par 2.4, and confirm with <sup>™</sup> . Press <sup>™</sup> to enter the starting menu 1.1.	Sensor tag 1.10 SENSOR	<ul> <li>OK Enter editing menu</li> <li>Select the value</li> <li>Modify the value</li> <li>OK Confirm</li> <li>Go to the next menu 1.1.</li> </ul>







<ul> <li>12.1 Peak values (3.1)</li> <li>In this menu are recorded the min. and max. distance values. They can be cleared to zero in menu 4.3.</li> <li>Press C to enter the next menu 3.2.</li> </ul>	Peak values     3.1       Distance-min     0.000 m (d)       Distance-max     2.109 m (d)	Go to the next menu 3.2.
<b>12.2 Measuremerent status (3.2)</b> The display shows the level of the receiving signal and the general status of the sensor. Press <sup>♀</sup> to enter menu <b>3.3</b> .	Meas status 3.2 Meas reliability: 10dB Sensor status: 0K	Go to the next menu 3.3.
1 <b>2.3 Choose curve (3.3)</b> Press <sup>™</sup> to enter curve selection and press <sup>™</sup> to enter menu <b>3.4</b> .	Choose curve 3.3 Echo curve►	OKEnter editing menuCo to the next menu 3.4.
Press 🔁 to select the curve and press 🚾 to confirm and to enter menu 3.4.	Choose curve 3.3 ► Echo curve False echo curve Output trend	Select curve Confirm and go to next menu 3.4.
<ul> <li>12.4 Echo curve (3.4)</li> <li>Press ∞ to enter zoom submenu of the selected curve. Press ∞ to enter the next menu 3.5.</li> <li>The 2 echo curve indicators show:</li> <li>4- actual measure</li> <li>Δ- estimated measure</li> <li>In normal operating conditions the indicators coincide in position and measure.</li> </ul>	Echo curve 10.000 3.4	OK Enter Zoom sub-menu Go to the next menu 3.5.







<ul> <li>13.1 False echo (4.1)</li> <li>This function gets rid of interferring signals caused by obstacles placed between the sensor and the product surface (i.e. brackets, agitators or pipes).</li> <li>Press IM to enter the False echo storing/modifying mode, press to enter the next menu 4.2.</li> <li>Press IM to select the function, then press IM to confirm and to enter the</li> </ul>	False Echo 4.1 Change?	ок	Enter the editing menu Go to the next menu 4.2.
The 0% level condition is the best way to record the False echo curve. In this way the system will monitor the whole path of the radar wave, intercepting all the obstacles that a product level > 0% would hide. Input the real actual distance that the system would measure.	False echo 4.1 Delete Update ► Create new	ОК	Select function Confirm selection and go to next sub-menu in case of update/create new
Check the correct distance from the product surface. In case of higher wrong input, the exsisting level would be recorded as false signal. As a con- sequence, the filling level will not be detected. Press of to set the parameter and to confirm. After the confirmation the system goes back to menu <b>4.1</b> .	False echo 4.1 update/create new 3.000 m (d)	CK	Select the digit Modify the value Confirm modification and start the recording false echo procedure
<b>13.2 Current output (4.2)</b> Press <sup>™</sup> to enter current output sub-menu, press <sup>™</sup> to enter the next menu 4.3	Current output 4.2 Output mode: 4-20mA Failure mode: no change Min. current: 4mA	ОК	Enter the editing menu Go to the next menu 4.3.
Press 🔁 to select the current output function, press 🚾 to confirm and en- ter the selected item, in sequence:	Current output 4.2 Current output mode Failure mode Min. current	ОК	Select mode Confirm and go to sub- menu
- Output mode; direct (4÷20mA) or indirect (20÷4mA) output. Press 🔁 to select the current output and then press 🚾 to confirm and to go back to sub-menu 4.2	0utput mode 4.2 4-20mA ► 20-4mA.	ОК	Select parameter Confirm and go to subme- nu 4.2.
<ul> <li>Failure mode; output signal forcing in case of system failure (no change/, 20.5mA or 22.0mA)</li> <li>Press to select the parameter and press to confirm and to go back to sub-menu 4.2</li> </ul>	Failure mode 4.2 No change ► 20.5mA 22.0mA.	ОК	Select parameter Confirm and go to subme- nu 4.2.



- Min. current; min.value of the signal (3.8mA or 4mA). Press 😂 to select the value and press 📧 to confirm and to go back to sub-menu 4.2	Min. current 4.2 3.8mA 4mA.	Select parameter OK Confirm and go to subme- nu 4.2.
13.3 Reset (4.3) Press ∞ to enter reset sub-menu, press ∞ to enter the next menu 4.4	Reset 4.3 Select reset ►	<b>OK</b> Enter the editing menu <b>Go</b> to the next menu 4.4.
Press <sup>Som</sup> to select the resetting parameters and press <sup>Som</sup> to confirm. The system is now reconfigured with default values.	Reset 4.3 ► Basic adjustment Factory settings Peak value menu	Select parameter OK Confirm and reset
13.4 Units of measurement (4.4) Press of to enter the units of measurement menu: metric system (m) or British system (ft). Press to enter the next menu 4.5.	Units of measurement 4.4 m (d) ►	OKEnter the editing menuCGo to the next menu 4.5.
<b>13.5 Language (4.5)</b> Press <sup>™</sup> to enter the language selection menu: Italian or English. Press <sup>™</sup> to enter the next menu <b>4.6</b> .	Language 4.5 English►	OKEnter the editing menuCGo to the next menu 4.6.
<b>13.6 HART operation mode (4.6)</b> Press <sup>OK</sup> to enter the HART operation mode: standard or multidrop. Press <sup>CO</sup> to enter the next menu <b>4.7</b> .	HART operation mode 4.6 Standard Address 0	OKEnter the editing menuCGo to the next menu 4.7.
Press to select HART communication mode: "Standard" (address0) or "Multidrop" (you must input the address. On the same line there cannot be 2 or more units with the same address). Press K to confirm: the system is now reconfigured with default values.	HART operation mode 4.6 Standard ► Multidrop	Select parameter OK Confirm and reset



13.7 Conv sensor data (4.7)		
Press K to enter the copy sensor data menu: copy from sensor or copy to	Copy sensor data 4.7	<b>OK</b> Enter the editing menu
sensor. Press 🗠 to enter the next menu 4.8	Copy sensor data r	Go to the next menu 4.8.
Press Sto select the operation: with "Copy from sensor", it is possible to save the sensor settings; with "Copy to sensor", all the previously saved sensor settings are restored. Press K to confirm: the system is now reconfigured with default values.	Copy sensor data4.7Copy from sensor ►Copy to sensor	Select the option
<b>13.8 PIN (4.8)</b> Press <sup>™</sup> to enter PIN sub-menu: if the PIN is inactive the option will be "Enable?".	PIN 4.7 Enable?	OK Enter editing menu Go back menu 4.1.
Press 🕅 to enter a 4 digit PIN code. If the PIN is active the option will be "Cancel?". Press 🔁 to go back to menu 4.1	PIN 4.7 Cancel ?	OK Enter editing menu Go back menu 4.1.
13.9 Distance Adj (4.9) Pressing <sup>™</sup> to access the distance adjustment. Press <sup>™</sup> to go back to next menu.	Distance Adj 4.9 +0.000m (d)	OKEnter editing menuCSelect the valueAndify the valueOKConfirmCo to the next menu
<b>13.10 Threshold (4.10)</b> With a low echo signal may be necessary to reduce the echo acquisition threshold (Echo Threshold). With a strong background noise may have to move higher up the echo curve zero line (Envelope Level). Press of to mo- dify the Echo Threshold value. Press of again to confirm and to edit the Envelope Level value. After the setup press of to confirm. Press of to enter next menu.	Threshold 4.10 Echo Threshold 60 dB Envelope Level 10 dB	OKEnter editing menuCSelect the valueCModify the valueOKConfirmCo to the next menu
<ul> <li>14. Info (5)</li> <li>From "RUN" mode press <sup>™</sup> to enter the configuration menu.</li> <li>The following menu will be displayed (1).</li> <li>Press <sup>™</sup> to select the item and <sup>™</sup> to confirm.</li> <li>The menu item number is always displayed on the top right corner.</li> <li>By selecting and confirming "Info" in menu 5, the display will show in sequence:</li> </ul>	Basic settings 5 Display Diagnostic Service ► Info	Select menu OK Confirm <u>Note-The menu item number is</u> <u>displayed on the top right corner</u>



<ul><li><b>14.1 Sensor type / Serial number (5.1)</b></li><li>Press  C to go to next menu 5.2.</li></ul>	Sensor type 5.1 Serial number 123456	Go to the next menu 5.2.
14.2 Date of manuf./ Software version (5.2) Press 🔁 to go back to menu 5.1	Date of manufacture <sup>5.2</sup> Software version	Go back to menu 5.1.



# 11. Troubleshooting

$\mathbf{A}$	Error Code	Error	Solution
<u>/:</u>	Err11	Power supply faulty	Use a multimeter to check whether the power supply of the product is outside the normal use range, please make sure that the power supply of the product is within the normal use range
	Err12	HART faulty	Check whether the load resistance (250 ohm) wiring is correct or not, and then check whether the communication between the product and the host computer is normal or not.
_	Err13	RS485 MODBUS faulty	First check RS485 communication wire positive and negative terminal is corrected connected according to indication, and confirm RS485 shift to RS232 communication shift module is work normal or not, the hardware connection make sure no problem, then make sure RS485 MODBUS instruction is send by instruction table info or not.
	Err14	Without receive effective echo wave signal	Check echo curve menu and make sure echo wave is exist or not, make sure the product enter blind zone or not, check range setting could satisfy actual application, then check the installation position could meet the requirements or not.
	Err15	Internal memory data read/write error	Send back to factory for repair.
	Err16	Device temperature exceeds the permit- ted range	It indicates electronic databank actual working temperature beyond-4085°C, pls make sure product operation within normal operation range.
	Err17	Device EEPROM data read /write error	Send back to factory for repair.
	Err18	System component parameters not match	Send back to factory for repair.





Riels instruments srl Viale Spagna, 16 35020 - Ponte San Nicolò (PD) - ITALY www.riels.it | info@riels.it | ph. +39 049 8961771